

Zhiyuan ZHANG

Ph.D, Assistant Professor

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Research Interests	
	Computer Vision / Graphics, Pattern Recognition, Machine Learning, 3D Point Cloud Deep Learning, 3D Shape Abstraction, 3D Shape Denoising, Biometrics
Honors & Awards	
	 Ningbo High Level Talent ("3315 Plan"), 2020-Present Shenzhen Peacock Program for Overseas High-Level Talent, 2016 - 2020 Pilot talent (Nanshan District, Shenzhen City), 2016 - 2020 NUS Research Full Scholarship, 2010 - 2014 The Hope Star of Science and Technology, Yanshan University, 2003
WORK EXPERIENCE	
Oct.2020 – Present	Assistant ProfessorNingbo Research Institute, Zhejiang University, ChinaLeading a research lab with focus on 3D vision.
Oct.2017 – Sept, 2020	 Research Fellow Singapore University of Technology and Design, Singapore Designed algorithms on 3D point cloud deep learning, and proposed novel efficient and rotation invariant convolution operators for point cloud understanding. Actively involved in the "AI in Metrology" project by designing innovative deep learning neural networks to generate CAD models, and matching between the CAD model and manufacturing model. Wrote academic papers, and supervised students.
Aug.2014 –Nov.2017	 Staff Researcher Lenovo Group Ltd. Hong Kong Research Centre Focused on computer vision projects with applications on dual camera calibration, image fusion, background blur, foreground enhancement, and so on. Proposed new ideas on product related problems and wrote patents
Oct.2008 –Oct.2009	 Visiting Scholar Department of Computing, The Hong Kong Polytechnic University Worked on '2D multi-view ear detection and recognition'. Designed system for online 3D ear point cloud capture and designed algorithm for 3D ear recognition
Aug.2005 –Jul.2006	 Training Specialist Shidai Computer Technique Training School, Qinhuangdao City, China Taught courses on C++ and Visual Basic Instructed students to pass the National Computer Rank Examination
EDUCATION	
Aug.2010 – May.2015	Doctor of Philosophy National University of Singapore, Singapore • thesis title: Improving Descriptors for 3D Shape Matching

- thesis url: https://scholarbank.nus.edu.sg/handle/10635/119782
- Focused on algorithms for both rigid and non-rigid 3D shape matching

Sep.2006 – Jul.2008	 Master's degree in Computer Science and Technology Harbin Institute of Technology, China Thesis Title: Reserch on Multi-View Ear Detection and Recognition (in Chinese). Focused on algorithms for biometrics e.g. ear detection and recognition
Sep.2001 - Jul.2005	Bachelors's degree in Computer Science and Technology School of Information Science and Engineering, Yanshan University, China
SKILLS	
Languages	Chinese – Native English – Full professional proficiency
Programming	C++, Python, MatLab, TensorFlow, MXNet, Pytorch, VTK
Communication	Excellent teaching and presentation ability Well collaboration with team members Active collaboration with external researchers
Publications	
	 Zhiyuan Zhang, Binh-Son Hua, Sai-Kit Yeung. "RIConv++: Effective Rotation Invariant Convolutions for 3D Point Clouds Deep Learning", International Journal of Computer Vision (IJCV), 2022 Xin Zhong, Zhiyuan Zhang. "3D Dental Biometrics: Automatic Pose-Invariant
	Dental Arch Extraction and Matching", International Conference on Pattern Re- cognition (ICPR) 2021
	 Zhiyuan Zhang, Binh-Son Hua, Wei Chen, Yibin Tian, Sai-Kit Yeung. "Global Context Aware Convolutions for 3D Point Cloud Understanding", International Conference on 3D Vision (3DV), 2020, Oral
	 Zhiyuan Zhang, Binh-Son Hua, Sai-Kit Yeung. "ShellNet: Efficient Point Cloud Convolutional Neural Networks using Concentric Shells Statistics", International Conference on Computer Vision (ICCV), 1607-1616, 2019, Oral, Accept Rate: 4.3%
	 Zhiyuan Zhang, Binh-Son Hua, David W. Rosen, Sai-Kit Yeung. "Rotation Invari- ant Convolutions for 3D Point Clouds Deep Learning", International Conference on 3D Vision (3DV), 204-213, 2019, Spotlight
	 Zhiyuan Zhang, Duc Thanh Nguyen, Lap-Fai Yu, Sai-Kit Yeung, Daniela Rus. "Creating Annotated Scene Meshes for Training and Testing Robot Systems", In- ternational Conference on Intelligent Robots (IROS) Tutorial, 2018
	• Zhiyuan Zhang , Sim Heng Ong, Xin Zhong, Kelvin W.C. Foong. "Efficient 3D Dental Identification via Signed Feature Histogram and Learning Keypoint Detection", Pattern Recognition (PR), Volume 60, 189-204, 2016
	 Zhiyuan Zhang, KangKang Yin, Kelvin W.C. Foong. "Symmetry Robust Descriptor for NonRigid Surface Matching", Computer Graphics Forum (Proc. Pa- cific Graphics), Volume 32,Issue 7, 355-362, 2013, Accept Rate: 19%
	 Zhiyuan Zhang, Xin Zhong, Sim Heng Ong, Kelvin W.C. Foong. "An Efficient Par- tial Shape Matching Algorithm for 3D Tooth Recognition", The 15th International Conference on BioMedical Engineering (ICBME), 785-788, 2013
	 Zhiyuan Zhang, Sim Heng Ong, Kelvin W.C. Foong. "Improved Spin Images for 3D Surface Matching using Signed Angles", IEEE International Conference on Image Processing (ICIP), 537-540, 2012
	 Heng Liu, David Zhang, Zhiyuan Zhang. "Multi-view Ear Recognition Based on Moving Least Square Pose Interpolation", Lecture Notes in Computer Science (Proc.ICIC), Volume 5755: 1085-1095, 2009
	 Zhiyuan Zhang, Heng Liu. "Multi-view Ear Recognition Based on B-Spline Pose Manifold Construction", The 7th World Congress on Intelligent Control and Auto- mation (WCICA): 2416-2421, 2008

- Committee Member for Siggraph Asia 2019 Courses
- **Invited Reviewer** for IROS 2020, Pacific Graphics 2019, 3DV 2019, ICRA 2019, Advanced Engineering Informatics, Pattern Recognition, Neural Computing and Applications

Patents

- **Zhiyuan Zhang**. Title: An information processing method and a electronic device, Patent No.: CN 106303203 B, 2015, China
- **Zhiyuan Zhang**. Title: An image fusion method and device, Patent No.: CN 106296624 A, 2015, China
- Wei Liu, **Zhiyuan Zhang**. Title: A method for image processing, Patent No.: CN 107644228 A, 2017, China
- **Zhiyuan Zhang**, Hao Li, Fan Zhang. Title: Image processing method and device, Patent No.: CN 108024062 A, 2017, China

Projects

- Al in Metrology, National Research Foundation, 332,880 SGD, Apr.2018-Mar.2020, Contributions: Designed generative neural networks to generate new CAD models; Designed efficient and rotation invariant convolution operators for 3D point cloud deep learning with applications on matching between CAD model and manufacturing model, point cloud classification and semantic segmentation.
- Shape Matching and Deformation Modeling for Kinect Depth Data, MSRA UR Project, 55,000 USD, May.2013-Jul.2014, Contributions: Focused non-rigid shape matching algorithms, proposed new non-rigid shape descriptors to match shape with severe deformation, and solve the symmetry flipping problem.

Additional Info

References Available on request

Hobbies Chess, Running, Reading, Travel